1 BCH Codes

For any positive integers $m \geq 3$ and $t \leq 2^{m-1}$, there exists a binary BCH code with the following parameters [3]

- Block length $n = 2^m - 1$

- Number of parity-check digits $n - k \leq m\delta$, with δ, the correcting capacity of the code and k the number of information bits

- Minimum distance $d_{min} \geq 2\delta + 1$

We denote this code by BCH$[n, k, \delta]$. Let α be the primitive element in GF(2^m), the generator polynomial $g(x)$ of the BCH$[n, k, \delta]$ code is given by:

$$g(x) = LCM\{\phi_1(x), \phi_2(x), \cdots, \phi_{2\delta}(x))\}$$

with $\phi_i(x)$ being the minimal polynomial of α^i (refer to [3] for more details on generator polynomial).

Depending on the parameters of the HQC scheme, we construct shortened BCH codes such that $k = 256$ from the two following BCH codes BCH-1 and BCH-2 (codes from [3]):

code	n	k	δ
BCH-1	1023	513	57
BCH-2	1023	483	60

We obtain the following shortened codes

code	n	k	δ
BCH-S1	766	256	57
BCH-S2	796	256	60

The shortened codes are obtained by substracting 257 (and 227) from BCH-1 (from BCH-2):

- BCH-S1$[766 = 1023 - 257, 256 = 513 - 257, 57]$

- BCH-S2$[796 = 1023 - 227, 256 = 483 - 227, 60]$

We notice that shortening the BCH code does not affect the correcting capacity.

In our case, we will be working in GF(2^{10}), for that we use the primitive polynomial of degree $1 + X^3 + X^{10}$ to build this field (polynomial from [3]). We precomputed the generator polynomials for the two codes that we will be using in our implementation (BCH-S1 and BCH-S2) and we included their Hexadecimal formats in the file parameters.h.

2 BCH Decoding

We give a brief reminder on decoding BCH codes following [3]. Consider the BCH code defined by $[n, k, \delta]$, with $n = 2^m - 1$ ($m \geq 0$ of positive integer) and suppose that a code word $v(x) = v_0 + v_1 x + \cdots + v_{n-1} x^{n-1}$ is transmitted and that during transmission, error occurred in the following received vector:

$$r(x) = r_0 + r_1 x + r_2 x^2 + \cdots + r_{n-1} x^{n-1}$$

We have that the location of errors are given by the error polynomial $e(x) = e_0 + e_1 x + e_2 x^2 + \cdots + e_{n-1} x^{n-1}$, if $e_i = 1$, then there is an error occurred at that location. Then we can write

$$r(x) = v(x) + e(x)$$

We define the set of syndromes $S_1, S_2, \cdots, S_{2\delta}$ as $S_i = r(\alpha^i)$, with α being the primitive element in $\mathrm{GF}(2^m)$. We have that $r(\alpha^i) = e(\alpha^i)$, since $v(\alpha^i) = 0$ (v is a code word). Suppose that $e(x)$ has t errors at locations $j_1, \cdots, j_t$, then

$$e(x) = x^{j_1} + x^{j_2} + \cdots + x^{j_t},$$

we obtain the following set of equations, where $\alpha^{j_1}, \alpha^{j_2}, \cdots, \alpha^{j_t}$ are unknown:

$$S_1 = \alpha^{j_1} + \alpha^{j_2} + \cdots + \alpha^{j_t}$$
$$S_2 = (\alpha^{j_1})^2 + (\alpha^{j_2})^2 + \cdots + (\alpha^{j_t})^2$$
$$S_3 = (\alpha^{j_1})^3 + (\alpha^{j_2})^3 + \cdots + (\alpha^{j_t})^3$$
$$\vdots$$
$$S_{2\delta} = (\alpha^{j_1})^{2\delta} + (\alpha^{j_2})^{2\delta} + \cdots + (\alpha^{j_t})^{2\delta}$$

The goal of a BCH decoding algorithm is to solve this system of equations. We define the error location numbers by $\beta_i = \alpha^{j_i}$, which indicate the location of the errors. The equations above, can be expressed as follows:

$$S_1 = \beta_1 + \beta_2 + \cdots + \beta_t$$
$$S_2 = \beta_1^2 + \beta_2^2 + \cdots + \beta_t^2$$
$$S_3 = \beta_1^3 + \beta_2^3 + \cdots + \beta_t^3$$
$$\vdots$$
$$S_{2\delta} = \beta_1^{2\delta} + \beta_2^{2\delta} + \cdots + \beta_t^{2\delta}$$

we define the error location polynomial as:

$$\sigma(x) = (1 + \beta_1 x)(1 + \beta_2 x) \cdots (1 + \beta_t x)$$
$$= 1 + \sigma_1 x + \sigma_2 x^2 + \cdots + \sigma_t x^t$$

We can see that, the roots of $\sigma(x)$ are $\beta_1^{-1}, \beta_2^{-1}, \cdots, \beta_t^{-1}$ which are the inverses of the error location numbers. By inverting those roots we can construct the error polynomial $e(x)$.

We can summarize the decoding procedure of a BCH$[n, k, \delta]$ code by the following steps:

1. The first step is the computation of $2 \times \delta$ syndromes using the received polynomial

2. The second step is the computation of the error-location polynomial $\sigma(x)$ from the $2 \times \delta$ syndromes computed in the first step (in our implementation we will use the Simplified Berlekamp's Algorithm [2])

3. The third step is to find the error-location numbers by calculating the roots of the polynomial $\sigma(x)$ and returning their inverse (in our implementation we will be using the Chien search algorithm [1])

4. The fourth step is the correction of errors in the received polynomial

Remark 1 *As mentioned before, in our implementation, we deal with shortened BCH code. We notice that we will be using the same decoding procedure described above.*

2.1 Syndromes computations

The following function compute the syndromes.

```
// bch.h
void syndrome_gen(syndrome_set* synd_set, gf_tables* tables, vector_u32* v)
```

The syndromes are computed by evaluating the received polynomial stored in the vector v at the $2\times$ PARAM DELTA consecutive roots of the generator polynomial $\alpha^i, i = 1, 2, \cdots, 2 * $ PARAM DELTA. Let us denote by $r(x)$ the polynomial in the vector v, thus the syndromes are

$$r(\alpha), r(\alpha^2), \cdots, r(\alpha^{2\times \text{PARAM DELTA}})$$

and they are stored as $\mathrm{GF}(2^{10})$ elements in the structure synd set which is the output the function.

2.2 Computing the Error-Location Polynomial

The following function compute the error location polynomial $\sigma(x)$ as defined above and store it in the vector sigma

```
// bch.h
void get_error_location_poly(sigma_poly* sigma, gf_tables* tables, syndrome_set* synd_set);
```

This function implements the simplified Berlekamp's algorithm for finding the error location polynomial for binary **BCH** codes given by Joiner and Komo in [2].

2.3 Finding the Error-Location Numbers

The following function computes the roots of the error location polynomial and find their inverses which are the error location numbers.

```
// bch.h
void chien_search(uint16_t* error_pos, uint16_t* size, gf_tables* tables, sigma_poly* sigma);
```

To find the roots of the polynomial $\sigma(x)$ stored in the structure sigma, we have to evaluate $\sigma(x)$ in all the element of the Galois Field: let α be the generator of the field then we have to check for $j = 1, 2, ...$ if $\sigma(\alpha^j) = 0$. Then if α^k is a root we store α^{-k} in the output array of the function. The Chien procedure permits to compute $\sigma(\alpha^{k+1})$ from $\sigma(\alpha^k)$, in fact :

- Suppose that σ is of degree t. If we have evaluated α^k, we obtain

$$\sigma(\alpha^k) = 1 + \sigma_1 \alpha^k + \sigma_2 \alpha^{2k} + \cdots + \sigma_t \alpha^{tk}$$

- Then, we can obtain $\sigma(\alpha^{k+1})$ in $O(t)$ operation. In fact the i-th term in $\sigma(\alpha^{k+1})$ can be obtained from the i-th term of $\sigma(\alpha^k)$ by multiplying that term by α^i.

  Suppose that we are using BCH$[n, k, \delta]$ one of the shortened BCH codes described bellow. Then, we have that the inverses of the roots of the elements α^i with $i \in \{1, \cdots, 2^{10} - 1 - n\}$ will not be a valid error positions. In fact the location number obtained will be grater than n. For that it is useless to evaluate the error location polynomial $\sigma(x)$ in the element α^i for $i \in \{1, \cdots, 2^{10} - 1 - n\}$. Therefore, in our implementation we starts the evaluation at α^i with $i = 2^{10} - n$.

2.4 Error correction

To correct the errors in the received polynomial: we have to build the error polynomial $e(x)$ using the error location numbers obtained by the Chien search algorithm, then we add the error polynomial to the received polynomial. The following function build $e(x)$ and store the result in the vector `e`

```
// bch.h
void error_poly_gen(vector_u32* e, uint16_t* error_pos, uint16_t size)
```

References

[1] Robert Chien. Cyclic decoding procedures for bose-chaudhuri-hocquenghem codes. *IEEE Transactions on information theory*, 10(4):357–363, 1964.

[2] Laurie L Joiner and John J Komo. Decoding binary bch codes. In *Southeastcon'95. Visualize the Future., Proceedings., IEEE*, pages 67–73. IEEE, 1995.

[3] Shu Lin and Daniel Costello. Error control coding: Fundamentals and applications. 1983.